L Number	Hits	Search Text	DB	Time stamp
4	67	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 11:06
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
•		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЈРО;	
:		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
		and controller) and (motor near2 power) and (three near2 phase near2	_	
		motor)		
6	200	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 12:22
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЈРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	,
		and controller) and (motor near2 power) and (current near3 torque)	i	
9	7	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 12:23
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЛРО;	
ŀ		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
		and controller) and (motor near2 power) and (current near3 torque near4		
		table)		
-	23	73/862.16.ccls.	USPAT;	2004/09/08 13:26
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM_TDB	
-	288	73/862.23.ccls.	USPAT;	2004/09/08 13:26
			US-PGPUB;	
			ЕРО; ЈРО;	
		·	DERWENT;	
			IBM_TDB	
- 1	105	73/862.27.ccls.	USPAT;	2004/09/08 13:27
			US-PGPUB;	
			ЕРО; ЛРО;	
Ī	Ì		DERWENT;	
	102	72/862 28 2012	IBM_TDB	2004/00/09 12:27
-	103	73/862.28.ccls.	USPAT; US-PGPUB;	2004/09/08 13:27
			EPO; JPO;	
			DERWENT;	
[IBM_TDB	
	119	73/862.29.ccls.	USPAT;	2004/09/08 13:27
-	119	757602.25.0018.	US-PGPUB;	2004/05/08 15.27
			EPO; JPO;	
1			DERWENT;	
			IBM_TDB	
_	70	73/862.193.ccls.	USPAT;	2004/09/08 13:48
			US-PGPUB;	200 110 15:10
			EPO; JPO;	
1			DERWENT;	
1			IBM_TDB	
_	4761	((motor engine) near4 control\$4) and (((ampere current) near2 (sensor	USPAT;	2004/09/08 14:00
		detect\$4 meter\$4)) or amper?meter) and (battery ac dc) and ((speed	US-PGPUB;	
-		velocity accelerometer) near4 (sensor detect\$4 meter\$4))	ЕРО; ЛРО;	
		, , , , , , , , , , , , , , , , , , , ,	DERWENT;	
			IBM_TDB	
-	2749	(((motor engine) near4 control\$4) and (((ampere current) near2 (sensor	USPAT;	2004/09/09 10:38
		detect\$4 meter\$4)) or amper?meter) and (battery ac dc) and ((speed	US-PGPUB;	
		velocity accelerometer) near4 (sensor detect\$4 meter\$4))) and ((torque	ЕРО, ЛРО,	
		torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4 determin\$4		1
1		torsion34 rotat34) near4 (sens34 detect34 meter34 determin34	DERWENT;	

_	4	("5543695" "5670856").pn.	USPAT;	2004/09/08 14:07
	,	(35,333,5 35,0335),pii.	US-PGPUB;	200 05 07
			ЕРО; ЈРО;	
			DERWENT;	
			IBM TDB	
-	1263	(((motor engine) near4 control\$4) and (((ampere current) near2 (sensor	USPĀT;	2004/09/09 10:40
		detect\$4 meter\$4)) or amper?meter) and (battery ac dc) and ((speed	US-PGPUB;	
		velocity accelerometer) near4 (sensor detect\$4 meter\$4))) and ((torque	ЕРО; ЈРО;	
		torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4 determin\$4	DERWENT;	
		estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
-	30	((((motor engine) near4 control\$4) and (((ampere current) near2 (sensor	USPAT;	2004/09/09 10:41
		detect\$4 meter\$4)) or amper?meter) and (battery ac dc) and ((speed	US-PGPUB,	
		velocity accelerometer) near4 (sensor detect\$4 meter\$4))) and ((torque	ЕРО; ЈРО;	
!		torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4 determin\$4	DERWENT;	
		estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)).clm.	IBM_TDB	
-	594	(((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/09 10:48
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЛРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
-	385	(((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/09 13:22
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЛРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
		and controller		
-	42	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/09 14:30
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	ЕРО; ЈРО;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
		and controller) and (electr\$4 near2 load)	TIODAT	2004/00/10 10 02
-	261	((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 10:03
		near2 (sensor detect\$4 meter\$4)) or amper?meter) and (battery ac dc)	US-PGPUB;	
		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	EPO; JPO;	
		and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
	<u> </u>	determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
1	65	and controller) and (motor near2 power) ((((motor engine) near4 control\$4 near3 electr\$5) and (((ampere current)	USPAT;	2004/09/10 12:21
-	03	near2 (sensor detect\$4 meter\$4)) or amper?meter) and ((ampere current)	US-PGPUB;	2004/03/10 12.21
1		and ((speed velocity accelerometer) near4 (sensor detect\$4 meter\$4)))	EPO; JPO;	
		and ((speed velocity accelerometer) hear4 (sensor detect\$4 meter\$4))) and ((torque torsion\$4 rotat\$4) near4 (sens\$4 detect\$4 meter\$4	DERWENT;	
		determin\$4 estimat\$4 asses\$4 calculat\$4)) and (torque near5 current)	IBM_TDB	
		and controller) and (motor near2 power) and (compar\$4 near3 torque)	11/1/1_1/1/1	
L	L	and conditioner) and (motor near 2 power) and (compared near 3 torque)	L	l